

Optics: Converging Mirror

Use the imaging rules you just learned to locate the image on the following diagrams:

Image A: Object is Beyond C

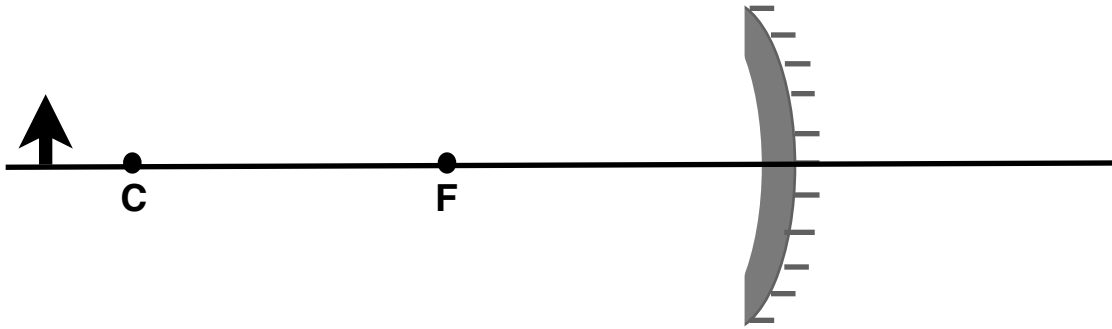


Image B: Object is At C

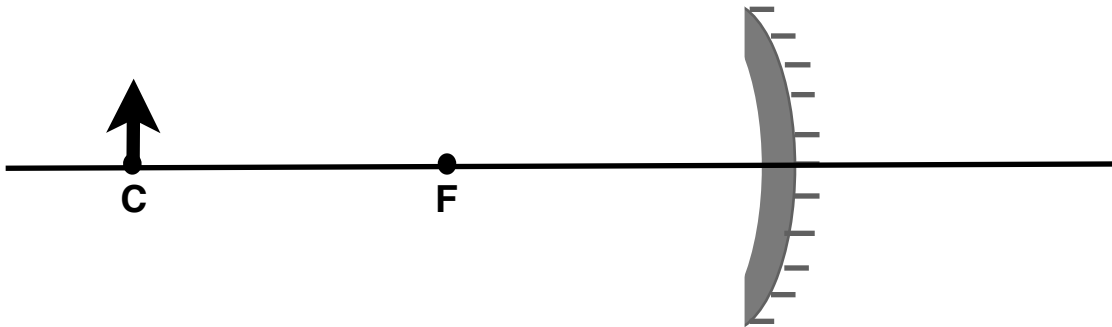


Image C: Object Between C and F

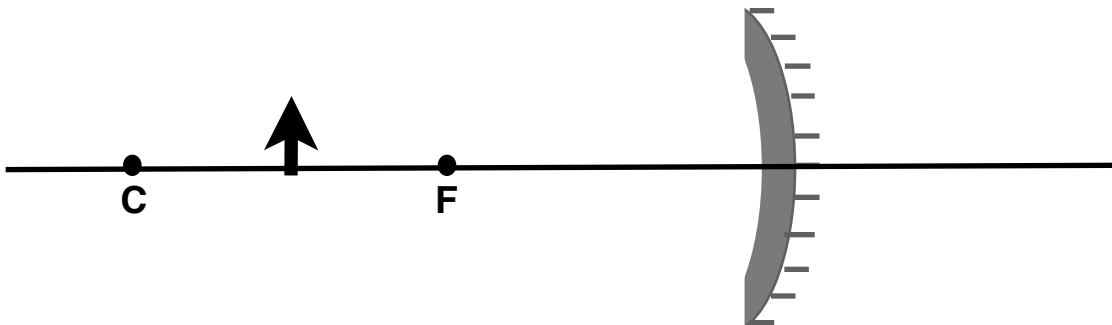


Image D: Object At F

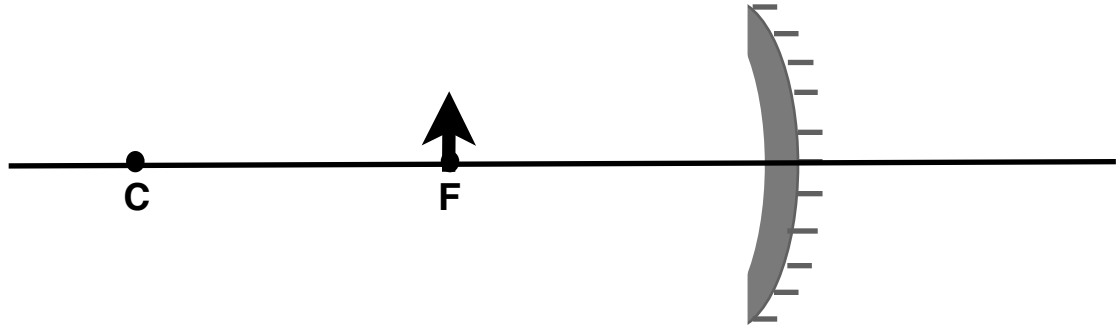
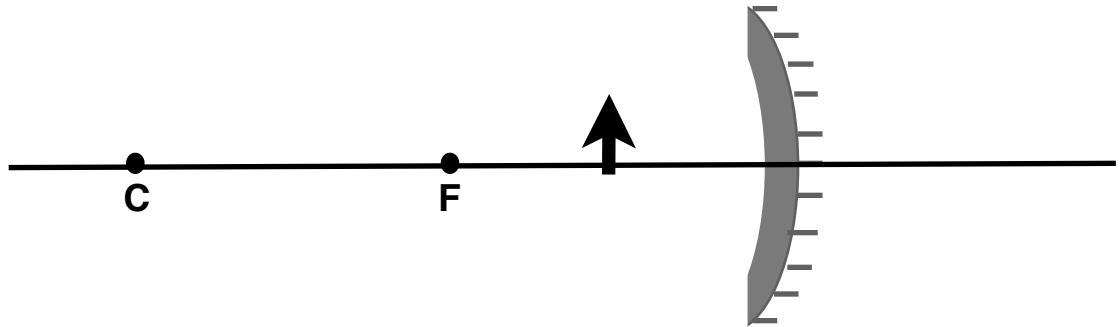


Image E: Object Inside F



OBJECT	IMAGE			
Location	Size (smaller, same, larger)	Attitude (Inverted, upright)	Location	Type (real or virtual)
Beyond C				
At C				
Between C and F				
At F				
Inside F				

SNC 2D