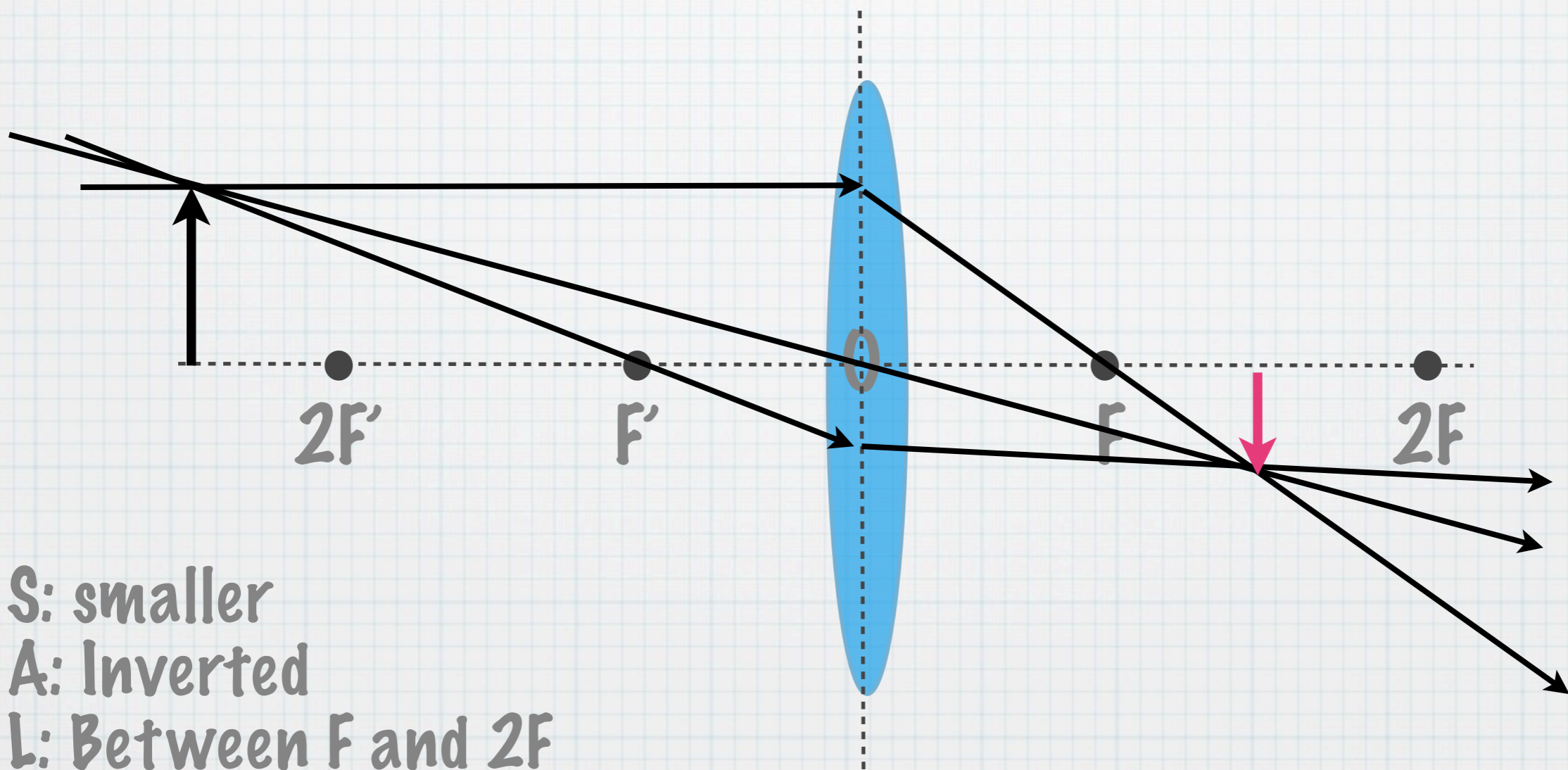


Image A: Beyond 2F



S: smaller
A: Inverted
L: Between F and $2F$
T: Real

Image B: At 2F

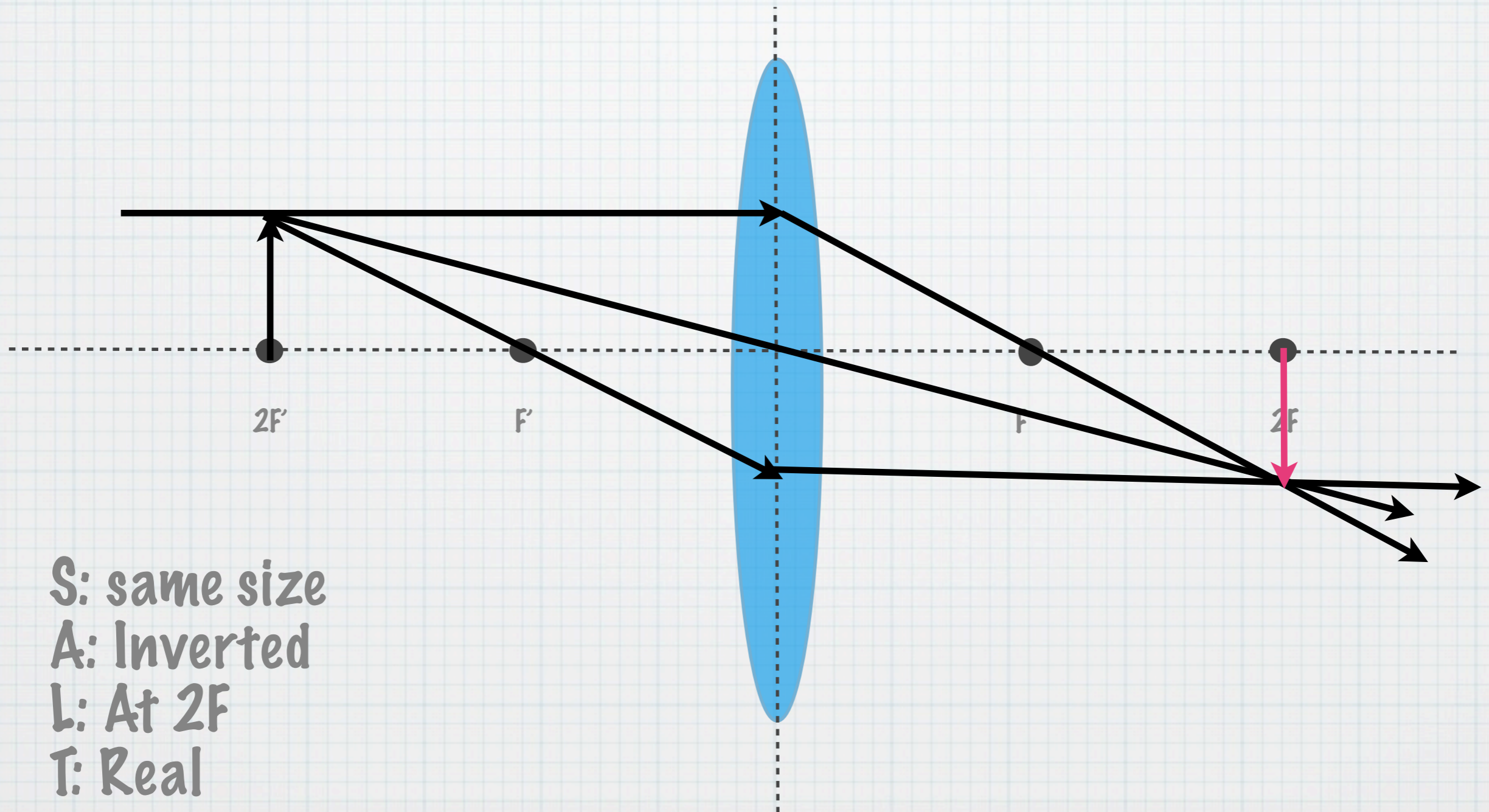
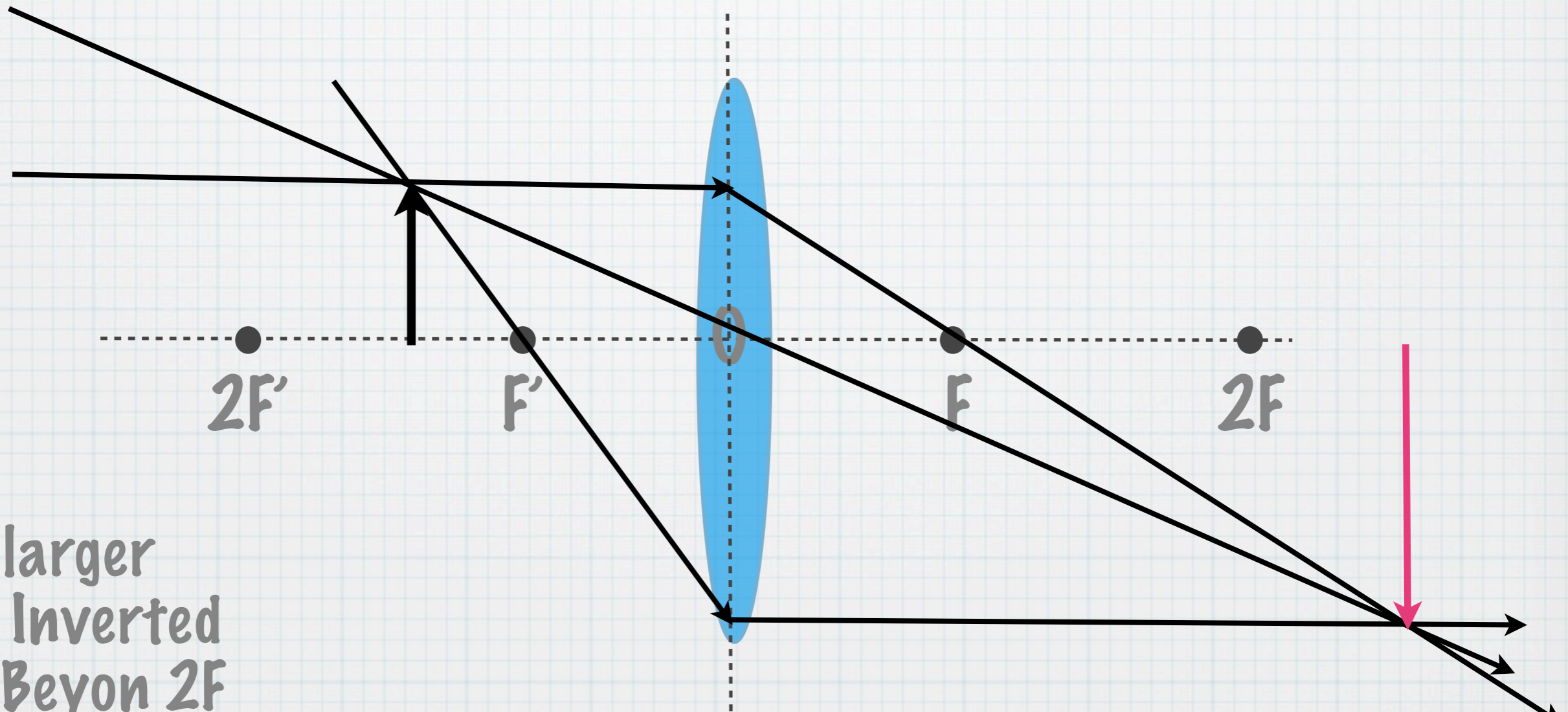


Image C: Between $2F$ and F



S: larger
A: Inverted
L: Beyond $2F$
T: Real

Image D: At F

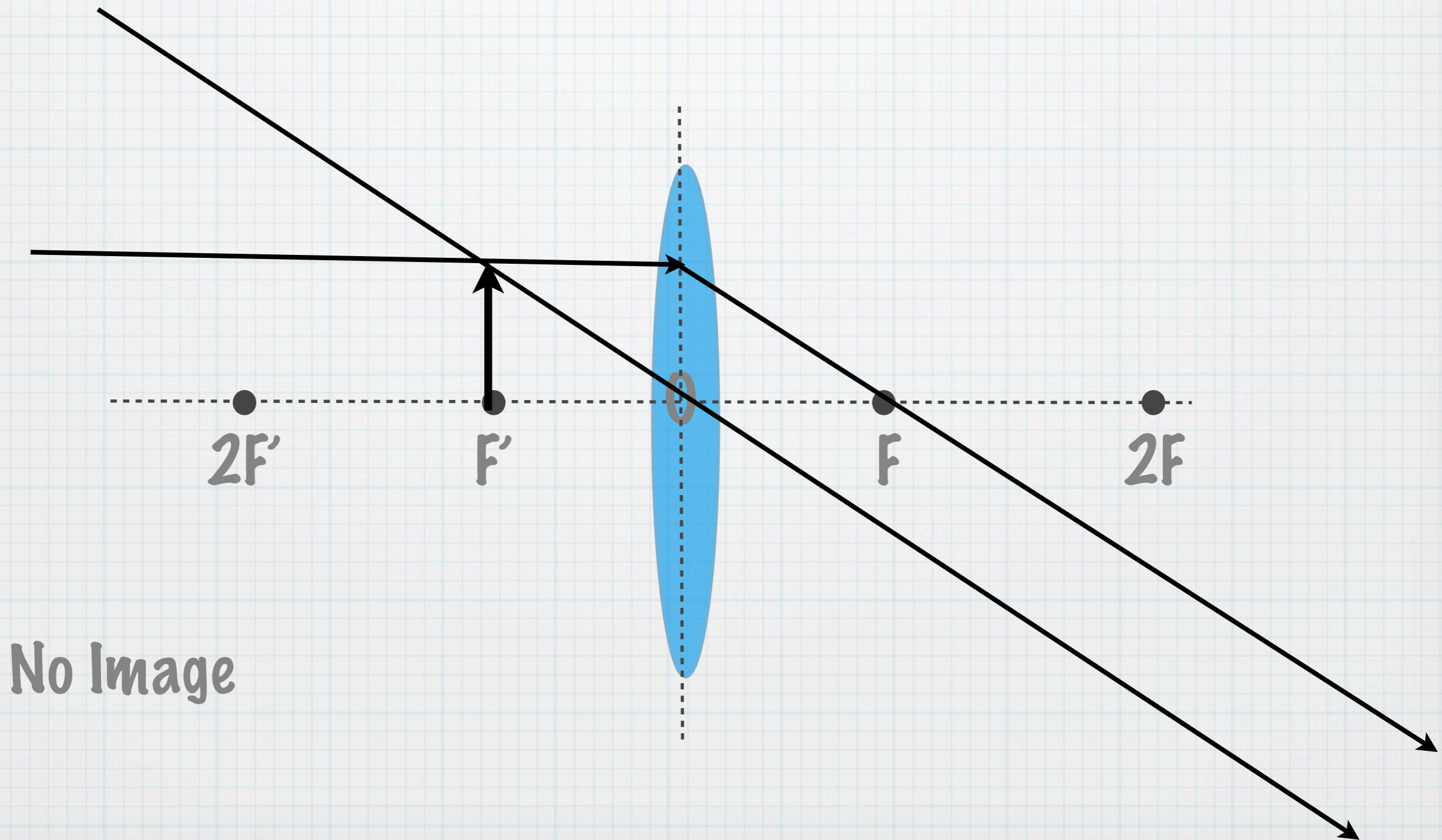
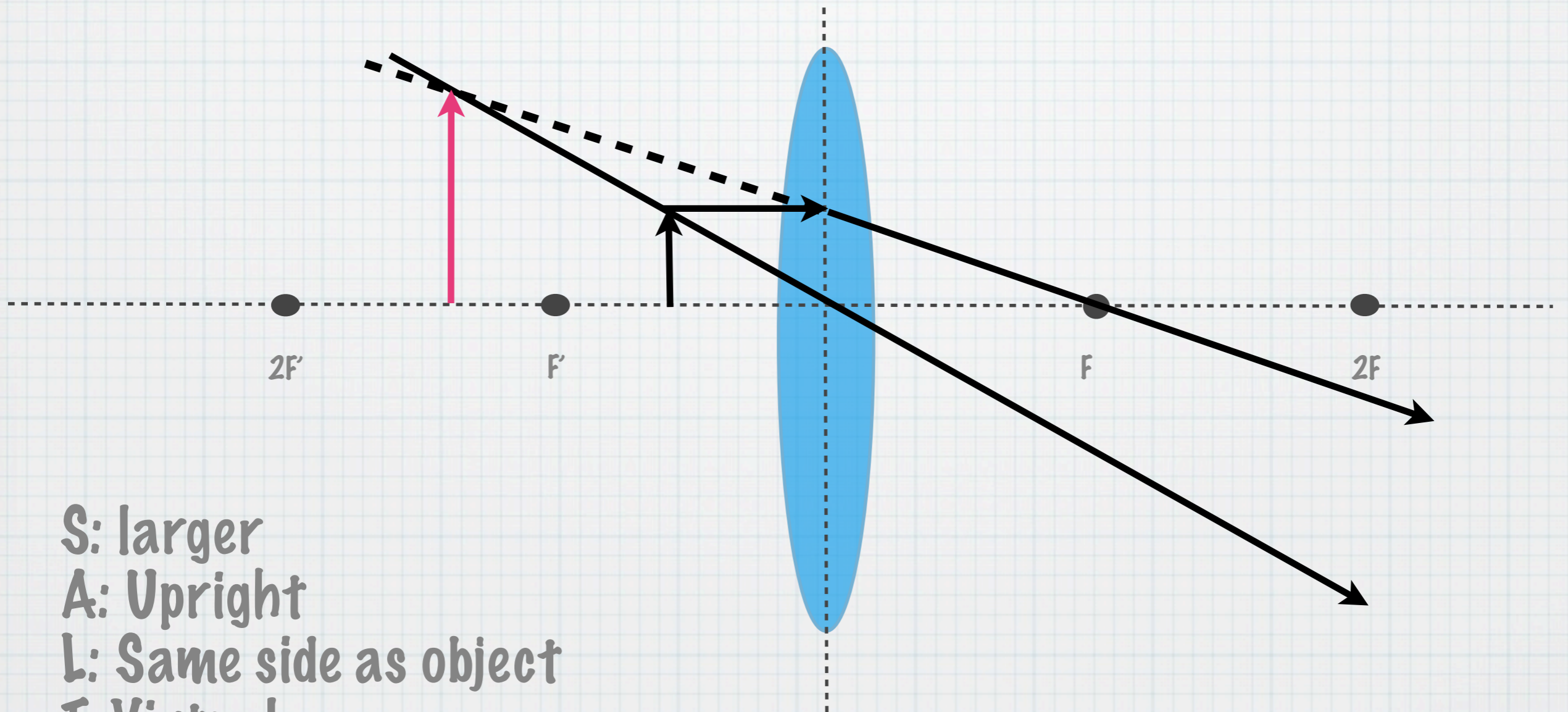
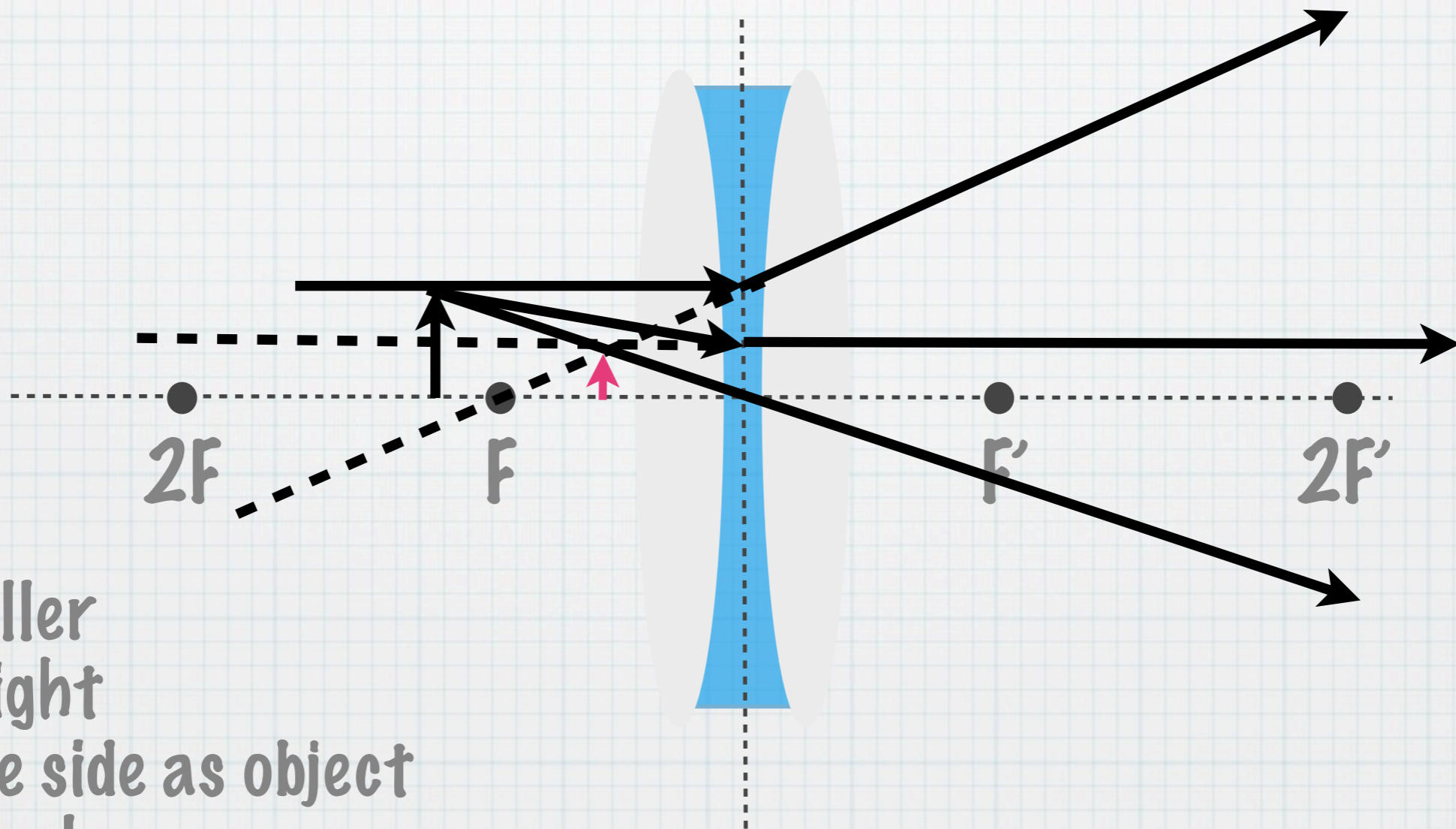


Image E: Before F



S: larger
A: Upright
L: Same side as object
T: Virtual

Image F: Diverging



S: smaller
A: upright
L: same side as object
T: Virtual